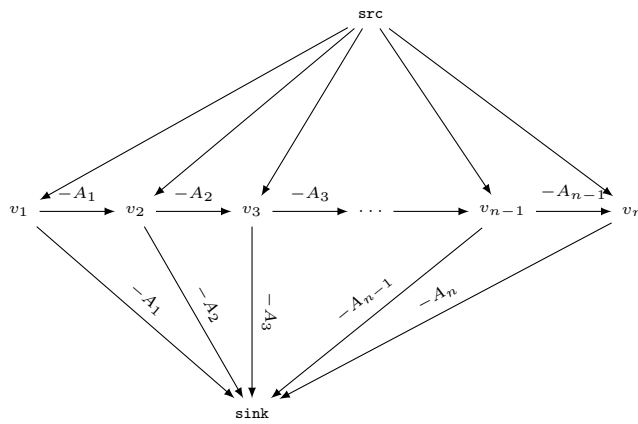


# Maximum Subarray Sum

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Given an array  $A$  of length  $n$  construct a directed graph as follows.  
Add vertices

- Add special vertices  $src, sink$ .
- Add one vertex  $v_i$  for each  $A_i$ .

$$V := \{src, sink\} \cup \{v_i \text{ for } 1 \leq i \leq n\}$$

Add edges

- Add edge of weight 0 from  $src$  to each  $v_i$ .
- Add edge of weight  $-A[i]$  from  $v_i$  to  $sink$ .
- Add edge of weight  $-A[i]$  from  $v_i$  to  $v_{i+1}$ .

$$E := \{(src, v_i, 0)\} \cup \{(v_i, sink, -A[i])\} \cup \{(v_i, v_{i+1}, -A[i])\}$$

We find shortest path from  $src$  to  $sink$ . -1 times cost of that path is our answer.

Now, you might be thinking Kadane's algorithm is just a few lines and this one will need a lot of code. Let me show you how little code is needed. This

is a DAG so we can find the shortest path by relaxing edges going out of vertices in topological order. We don't need to implement topological sort because we already know the order i.e.  $sink, v_n, v_{n-1}, \dots, v_0, src$ .

MAX-SUBARRAY-SUM( $A$ )

```

1  d[v] = 0 for  $v \in V$ 
2  d[vn] = -A[n]
3  for  $v_i = v_{n-1}, \dots, v_1, src$ 
4      for  $v \in Adj[v_i]$ 
5          RELAX( $v_i, v, weight(v_i, v)$ )
6  return -min{d[v] for  $v \in V$  }
```

We know there are only two outgoing edges from the vertices being relaxed. We replace RELAX by its implementation for each of those edges to get the code below.

Substitute adjacent vertices.

MAX-SUBARRAY-SUM( $A$ )

```

1  d[v] = 0 for  $v \in V$ 
2  d[vn] = -A[n]
3  for  $v_i = v_{n-1}, \dots, v_1, src$ 
4      RELAX( $v_i, v_{i+1}, weight(v_i, v_{i+1})$ )
5      RELAX( $v_i, sink, weight(v_i, sink)$ )
6  return -min{d[v] for  $v \in V$  }
```

Substitute weights.

MAX-SUBARRAY-SUM( $A$ )

```

1  d[v] = 0 for  $v \in V$ 
2  d[vn] = -A[n]
3  for  $v_i = v_{n-1}, \dots, v_1, src$ 
4      RELAX( $v_i, v_{i+1}, -A[i]$ )
5      RELAX( $v_i, sink, -A[i]$ )
6  return -min{d[v] for  $v \in V$  }
```

Substitute implementation of RELAX.

MAX-SUBARRAY-SUM( $A$ )

```

1  d[v] = 0 for  $v \in V$ 
2  d[vn] = -A[n]
3  for  $v_i = v_{n-1}, \dots, v_1, src$ 
4      d[vi] = min(d[vi], d[vi+1] - A[i])
5      d[vi] = min(d[vi], d[sink] - A[i])
6  return -min{d[v] for  $v \in V$  }
```

This in turn is equivalent to the following final code since  $d[sink] = 0$ .

MAX-SUBARRAY-SUM( $A$ )

```
1   $d[v] = 0$  for  $v \in V$ 
2   $d[v_n] = -A[n]$ 
3  for  $v_i = v_{n-1}, \dots, v_1, src$ 
4       $d[v_i] = \min(-A[i], d[v_{i+1}] - A[i])$ 
5  return  $-\min\{d[v] \text{ for } v \in V\}$ 
```

Here is go lang implementation

```
func maxSubarraySum(A []int) int {  
    n := len(A)  
    d := make([]int, n)  
    d[n-1] = -A[n-1]  
    for i := n-2; i >= 0; i-- {  
        d[i] = min(-A[i], -A[i] + d[i+1])  
    }  
    return -slices.Min(d)  
}
```

We could maintain the global min while looping instead of computing it at the end using `slices.Min`.

```
func maxSubarraySum(A []int) int {  
    n := len(A)  
    d := make([]int, n)  
  
    d[n-1] = -A[n-1]  
    minn := d[n-1]  
    for i := n-2; i >= 0; i-- {  
        d[i] = min(-A[i], -A[i] + d[i+1])  
        minn = min(minn, d[i])  
    }  
    return -minn  
}
```

Looks exactly like Kadane's algorithm, doesn't it?